

NOTE 1. LINEAR SYSTEM

Finite vs. Infinite Duration Signals

A discrete signal $x[n]$ is finite duration if there exists two integers $-\infty < N_1 \leq N_2 < \infty$, such that $x[n] \neq 0$ only for $N_1 \leq n \leq N_2$.

Otherwise, it is of infinite duration.

Right-sided, Left-sided, and Two-sided Signals

The terms apply only to infinite duration signals.

If there exists an integer N_1 such that $x[n] \neq 0$ only for $n \geq N_1$, then $x[n]$ is right-sided.

If there exists an integer N_2 such that $x[n] \neq 0$ only for $n \leq N_2$, then $x[n]$ is left-sided.

If $x[n]$ is neither right-sided nor left-sided, then it is two-sided.

Causal and Anti-Causal Signals

A signal $x[n]$ is causal if $x[n] = 0$ for all $n < 0$.

A signal $x[n]$ is anti-causal if $x[n] = 0$ for all $n > 0$.

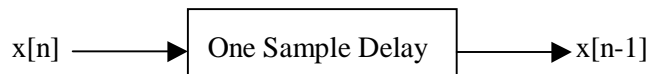
4. Zero phase, linear phase and nonlinear phase signals

Zero Phase: Left-right symmetry around sample number zero.

Linear Phase: Left-right symmetry around sample number other than zero. Linear phase signal can be changed to zero phase one by simple shifting.

Nonlinear Phase: without left-right symmetry.

5. Time Delay



System (Transform, Mapping): A Relationship between Input and Output.

7. Linear System S can be characterized by the following conditions:

Homogeneity:

For constant k ,

if system S satisfies $S(x[n]) = y[n]$,

then $S(kx[n]) = kS(x[n]) = ky[n]$.

Additivity:

If $S(x_1[n]) = y_1[n]$, and $S(x_2[n]) = y_2[n]$

Then $S(x_1[n] + x_2[n]) = S(x_1[n]) + S(x_2[n]) = y_1[n] + y_2[n]$

Commutative:

for linear systems A and B

$A(B(x[n])) = B(A(x[n]))$

Any System violates above-mentioned three rules, is a nonlinear system.

8. Shift (Time) Invariance System:

if $S(x[n]) = y[n]$, then $S(x[n + i]) = y[n + i]$.

9. Energy of signal $x[n]$:
$$E = \sum_{n=-\infty}^{\infty} |x[n]|^2 .$$

NOTE 2. Convolution

Convolution – most important technique in DSP, by combining two (or more) signals to form a third output.

Signal Filtering (Estimation), Function Approximation

Interpolation

Prediction (extrapolation)

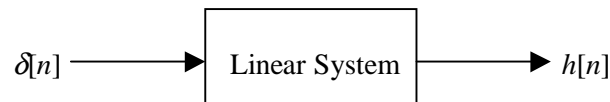
Definition 1: Delta Function (Unit Impulse) $\delta[n] = \begin{cases} 1, & n = 0 \\ 0, & \text{others} \end{cases}$

Standard Function $u(n) = \begin{cases} 1, & n \geq 0 \\ 0, & \text{others} \end{cases}$

$$\delta[n] = u[n] - u[n - 1]$$

$$u[n] = \sum_{k=0}^{\infty} \delta(n - k)$$

Definition 2: Impulse response $h[n]$ of linear system S . The signal that exits a system when a Delta Function (unit impulse) is the input.



$$h[n] = S(\delta[n])$$

Any sequence $x[n]$ can be represented by weighted Delta function

$$x[n] = \sum_{k=-\infty}^{\infty} x(k)\delta(n - k)$$

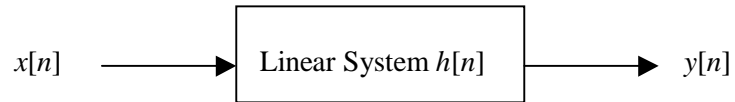
Definition 3: Periodic Sequence

$$x[n] = x[n + N]$$

Example:

$\sin[2\pi f(n+N)] = \sin[2\pi fn]$, f is normalized frequency.

Definition 4: Convolution $y[n] = h[n] * x[n]$



The impulse response of the system expresses the relation between input and output.

$$y[i] = \sum_{j=-\infty}^{\infty} h[j]x[i-j]$$

Convolution Sum (Linear System).

NOTE 3. Convolution Properties

Properties of Delta function: $\delta[n]$ is identity for convolution,

$$x[n] * \delta[n] = x[n]$$

$$x[n] * k\delta[n] = kx[n]$$

$$x[n] * \delta[n + i] = x[n + i]$$

Properties of Convolution (Convolution is a linear system)

Commutative: $a[n] * b[n] = b[n] * a[n]$

Associative: $\{a[n] * b[n]\} * c[n] = a[n] * \{b[n] * c[n]\}$

Distributive: $a[n] * b[n] + a[n] * c[n] = a[n] * \{b[n] + c[n]\}$

Transference between the Input and Output

Suppose $y[n] = x[n] * h[n]$,

If L is a linear system and $x_1[n] = L\{x[n]\}$, $y_1[n] = L\{y[n]\}$

Then $y_1[n] = x_1[n] * h[n]$

5. (Auto-Regression): $y[n] = \sum_{k=0}^{M-1} a[k]x[n-k]$

For Example: $y[n] = x[n] - x[n-1]$ (first difference)

6. (Moving Average): $y[n] = b[0]x[n] + \sum_{k=1}^{M-1} b[k]y[n-k]$

For Example: $y[n] = x[n] + y[n-1]$ (running sum)

7. Central Limit Theorem: $y[n] = x[n] * x[n] * \dots * x[n]$

8. Correlation: Convolution = Cross-Correlation $c[n] = a[n] * b[-n]$

Autocorrelation: $c[n] = a[n] * a[-n]$

Detector (Not Restoration).

Low-Pass Filter $h[n]$: $\sum_n h[n] \neq 0$, $\sum_n (-1)^n h[n] = 0$

Cutoff the high-frequency components (undulation, pitches), smooth the signal

High-pass Filter $h[n]$: $\sum_n h[n] = 0$

Only preserve the quick undulation terms

Delta function: All-pass filter $x[n] = x[n] * \delta[n]$

NOTE 4. Fourier Representation

Any continuous periodic signal \Leftrightarrow sum of properly chosen sinusoidal functions

Gibbs Effects: Problem of non-smooth continuous

4 Categories of Fourier Representation ($\omega = 2\pi f$)

(1) Aperiodic Continuous Fourier Transform

$$X(f) = \int_{-\infty}^{+\infty} x(t)e^{-j2\pi ft} dt$$

Aperiodic

Frequency $f \in \mathbb{R}$ Continuous

Time (Shift) $t \in \mathbb{R}$ Continuous

(2) Periodic Continuous Fourier Series (Frequency Response)

$$X(f) = \sum_{n=-\infty}^{+\infty} x(n)e^{-j2\pi fn}$$

Use to Characterize the Filters and Signals. Response

Periodic $X(f) = X(f + 1)$

Frequency $f \in \mathbb{R}$ Continuous

Time (Shift) $k \in \mathbb{Z}$ Discrete

Aperiodic Discrete Time Fourier Transform

$$X(k) = \int_{-\infty}^{+\infty} x(t)e^{-j2\pi k\Delta t} dt$$

Aperiodic

Frequency $k \in \mathbb{Z}$ Discrete

Time (Shift) $t \in \mathbb{R}$ Continuous

(4) Periodic Discrete Fourier Transform

$$X[k] = \sum_{i=0}^{N-1} x[i]e^{-j2\pi ki/N}$$

$$e^{-j2\pi ki/N} = \cos(2\pi ki/N) - j\sin(2\pi ki/N)$$

$$X[k] = \sum_{i=0}^{N-1} x[i] \cos(2\pi ki / N) - j \sum_{i=0}^{N-1} x[i] \sin(2\pi ki / N)$$

| | | |
|--------------|--------------------|----------|
| Periodic | $X(k + N) = X(k)$ | |
| Frequency | $k \in \mathbb{Z}$ | Discrete |
| Time (Shift) | $n \in \mathbb{Z}$ | Discrete |

Frequency Response Frequency Transform of Sequence $h[n]$

$$H(\omega) = \sum_{k=-\infty}^{\infty} h[k] e^{-jk\omega}$$

Inverse Frequency Transform

$$h[k] = \frac{1}{2\pi} \int_{-\pi}^{\pi} H(\omega) e^{jk\omega} d\omega$$

Continuous

Periodic $H(\omega + 2\pi) = H(\omega)$

≠ Discrete Fourier Transform (DFT)

Ideal Low-pass Filter

$$H(\omega) = \begin{cases} 1, & |\omega| \leq \frac{\pi}{2} \\ 0, & \frac{\pi}{2} < |\omega| \leq \frac{\pi}{2} \end{cases}$$

Inverse Frequency Response

$$h[k] = \frac{1}{2\pi} \int_{-\pi}^{\pi} H(\omega) e^{jk\omega} d\omega = \frac{1}{2\pi} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} e^{jk\omega} d\omega = \frac{\sin\left(\frac{k\pi}{2}\right)}{k\pi}$$

Not Causal

Technically CAN NOT be Realized

Cut-off cause Gibbs Oscillation

Frequency Transform of Convolution

$$y[n] = h[n] * x[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

$$Y(\omega) = X(\omega)H(\omega)$$

NOTE 5. Properties of Frequency Response

Periodic Continuous Fourier Series

$$X(\omega) = \sum_{n=-\infty}^{+\infty} x(n)e^{-j\omega n}$$

Frequency Response of Convolution

$$y[n] = h[n] * x[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

$$\Downarrow$$

$$Y(\omega) = X(\omega)H(\omega)$$

$$H(\omega) = Y(\omega) / X(\omega) \quad \text{Transfer Function of the Linear System}$$

$$|H(\omega)| = [\text{Im } H(\omega)^2 + \text{Re } H(\omega)^2]^{1/2} \quad \text{Magnitude of Transfer Function}$$

$$\text{Arg}(H(\omega)) = \arctan(\text{Im } H(\omega) / \text{Re } H(\omega)) \quad \text{Phase of Transfer Function}$$

$$\text{Even Symmetry around Point Zero} \quad x[n] = x[-n]$$

$$X(\omega) = \sum_{n=-\infty}^{+\infty} x(n)e^{-j\omega n}$$

$$= x[0] + \sum_{n=1}^{\infty} (x[n]e^{-j\omega n} + x[-n]e^{j\omega n})$$

$$= x[0] + \sum_{n=1}^{\infty} x[n](e^{-j\omega n} + e^{j\omega n})$$

$$= x[0] + 2 \sum_{n=1}^{\infty} x[n] \cos(\omega n)$$

Real Spectrum

$$\text{Phase Arg}(H(\omega)) = 0 \quad \text{Zero-phase Signal}$$

$$\text{Odd Symmetry around Point Zero} \quad x[n] = -x[-n], \quad x[0] = 0$$

$$\begin{aligned}
X(\omega) &= \sum_{n=-\infty}^{+\infty} x(n)e^{-j\omega n} \\
&= x[0] + \sum_{n=1}^{\infty} (x[n]e^{-j\omega n} + x[-n]e^{j\omega n}) \\
&= \sum_{n=1}^{\infty} x[n](e^{-j\omega n} - e^{j\omega n}) \\
&= -2j \sum_{n=1}^{\infty} x[n]\sin(\omega n)
\end{aligned}$$

Complex Spectrum

$$\text{Phase Arg}(H(\omega)) = -\pi/2$$

Even Symmetry around sample number N other than zero $x[N+n] = x[N-n]$

$$\begin{aligned}
X(\omega) &= \sum_{k=-\infty}^{+\infty} x(k)e^{-j\omega k} \\
&= x[N]e^{-j\omega N} + \sum_{k=-\infty}^{N-1} x[k]e^{-j\omega k} + \sum_{k=N+1}^{\infty} x[k]e^{-j\omega k} \\
&= x[N]e^{-j\omega N} + e^{-j\omega N} \sum_{n=1}^{\infty} x[n+N](e^{j\omega n} + e^{-j\omega n}) \\
&= e^{-j\omega N} \{x[N] + 2 \sum_{n=1}^{\infty} x[n+N]\cos(\omega n)\}
\end{aligned}$$

Complex Spectrum

$$\text{Phase Arg}(H(\omega)) = -N\omega \quad \text{Linear-phase Signal}$$

$$\text{Odd-symmetric signal} \quad \text{Generalized linear-phase signal}$$

Even/Odd Decomposition of any Real Signal $x[n]$

$$\text{Even Symmetry } x_e[n] = (x[n] + x[-n]) / 2$$

$$x_e[n] = x_e[-n]$$

$$\text{Odd Symmetry } x_o[n] = (x[n] - x[-n])/2$$

$$x_o[n] = -x_o[-n]$$

Even Symmetry Sequence $x_e[n]$ generate real spectrum

Odd Symmetry Sequence $x_o[n]$ generate complex spectrum

(4) $x[n] \longrightarrow X(\omega)$



$x[-n] \longrightarrow \overline{X(\omega)}$

NOTE 6. Digital Fourier Transform (DFT)

Periodic Continuous Fourier Series of $x[n]$, $n = 0, N-1$

$$X(\omega) = \sum_{n=0}^{N-1} x[n] e^{-j\omega n}$$

Let $\omega = 2\pi k / N$, $k = 0, N-1$

$$X[k] = X(\omega) \big|_{\omega=2\pi k / N} = \sum_{n=0}^{N-1} x[n] e^{-j2\pi kn / N}$$

Periodic Discrete Fourier Transform of Real Signal

$$e^{-j2\pi ki / N} = \cos(2\pi ki / N) - j \sin(2\pi ki / N)$$

$$\operatorname{Re} X[k] = \sum_{i=0}^{N-1} x[i] \cos(2\pi ki / N)$$

$$\operatorname{Im} X[k] = -\sum_{i=0}^{N-1} x[i] \sin(2\pi ki / N)$$

Periodic Character

$$X[k + N] = X[k]$$

Inverse Discrete Fourier Transform

$$\sum_{k=0}^{N-1} X[k] e^{j2\pi km / N} = \sum_{k=0}^{N-1} \left\{ \sum_{n=0}^{N-1} x[n] e^{-j2\pi kn / N} \right\} e^{j2\pi km / N} = \sum_{n=0}^{N-1} x[n] \left\{ \sum_{k=0}^{N-1} e^{j2\pi k(m-n) / N} \right\}$$

Because
$$\sum_{k=0}^{N-1} e^{j2\pi k(m-n) / N} = \begin{cases} N, & m = n \\ 0, & m \neq n \end{cases}$$

Then
$$\sum_{k=0}^{N-1} X[k] e^{j2\pi km / N} = Nx[m]$$

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi kn/N}$$

Simplified Algorithm

$$X[N-k] = \sum_{n=0}^{N-1} x[n] e^{-j2\pi(N-k)n/N} = \sum_{n=0}^{N-1} x[n] e^{j2\pi kn/N}$$

$$\operatorname{Re} X[N-k] = \operatorname{Re} X[k] \quad \operatorname{Im} X[N-k] = -\operatorname{Im} X[k]$$

$$|X[N-k]| = |X[k]|, \quad \operatorname{Arg}(X[N-k]) = -\operatorname{Arg} X[k]$$

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi kn/N} = \frac{1}{N} \sum_{k=0}^{N-1} \operatorname{Re} X[k] \cos(2\pi kn/N) - \frac{1}{N} \sum_{k=0}^{N-1} \operatorname{Im} X[k] \sin(2\pi kn/N)$$

$$\cos(2\pi(N-k)n/N) = \cos(2\pi kn/N)$$

$$\sin(2\pi(N-k)n/N) = -\sin(2\pi kn/N)$$

$$x[n] = \{\operatorname{Re} X[0] + \operatorname{Re} X[N/2] \cos(n\pi)\} / N$$

$$+ \frac{2}{N} \sum_{k=1}^{N/2-1} \operatorname{Re} X[k] \cos(2\pi kn/N) - \frac{2}{N} \sum_{k=1}^{N/2-1} \operatorname{Im} X[k] \sin(2\pi kn/N)$$

NOTE 7: CHARACTERISTICS OF DFT

Linear: If $x[n] = ax_1[n] + bx_2[n]$, then $X[k] = aX_1[k] + bX_2[k]$.

Circular Shift:

$$\text{Time: } DFT(x[n-m]) = e^{-j2\pi km/N} X[k]$$

$$\text{Frequency: } IDFT(X[k-l]) = e^{j2\pi ml/N} X[k]$$

Circular Convolution

$$\text{If } y[n] = x_1[n] * x_2[n] = \sum_{m=0}^{N-1} x_1[m]x_2[n-m], \text{ then } Y[k] = X_1[k]X_2[k].$$

$$\text{If } Y[k] = X_1[k] * X_2[k] = \frac{1}{N} \sum_{m=0}^{N-1} X_1[m]X_2[k-m], \text{ then } y[n] = x_1[n]x_2[n].$$

Non-Overlap Condition

$x_1[n]$: L non-zero,

$x_2[n]$: M non-zero

The zero-extended period duration $N \geq L + M - 1$

Inverse DFT (can be implemented using the same program of DFT)

$$x[n] = \frac{1}{N} \sum_{m=0}^{N-1} X[m]e^{j2\pi mn/N} = \frac{1}{N} \left(\sum_{m=0}^{N-1} X^*[m]e^{-j2\pi mn/N} \right)^*$$

$$\text{DFT: } X[k] = \sum_{m=0}^{N-1} x[m]e^{-j2\pi km/N}$$

Symmetry Theorem

If $DFT(x[n]) = X[k]$, then $DFT(x[-n]) = X[-k]$

$$DFT\left(\frac{X[k]}{N}\right) = x[-n]$$

Initial State

$$\text{Frequency Domain } X[0] = \sum_{n=0}^{N-1} x[n]$$

$$\text{Time Domain } x[0] = \frac{1}{N} \sum_{k=0}^{N-1} X[k]$$

Zero Extension

Time Domain

$$\text{If } g[n] = \begin{cases} x[n], & 0 \leq n \leq N-1 \\ 0, & N \leq n \leq rN-1 \end{cases}, \text{ then } G[k] = DFT(g[n]) = X\left(\frac{k}{r}\right)$$

Frequency Domain

$$\text{If } Y[k] = \begin{cases} X[k], & 0 \leq k \leq N-1 \\ 0, & N \leq k \leq rN-1 \end{cases}, \text{ then } y[n] = IDFT(Y[k]) = \frac{1}{r} x\left(\frac{n}{r}\right), \quad k = 0, rN-1.$$

Discrete Cosine Transform
 Orthogonal Transform
 Symmetry-Periodic Extension
 $x[-n] = x[n]$

JPEG (Joint Photographic Expert Group)
 MPEG (Moving Picture Expert Group)

$$\text{DCT} \quad X[k] = \sqrt{\frac{2}{N}} a[k] \sum_{n=0}^{N-1} x[n] \cos\left(\frac{(2n+1)k\pi}{2N}\right)$$

$$\text{IDCT} \quad x[n] = \sqrt{\frac{2}{N}} \sum_{k=0}^{N-1} a[k] X[k] \cos\left(\frac{(2n+1)k\pi}{2N}\right)$$

$$\text{where } a[k] = \begin{cases} \frac{\sqrt{2}}{2}, & k = 0 \\ 1, & \text{else} \end{cases}$$

DCT and IDCT share the same transformation kernel

Real spectrum, can be implemented by 2N-dot FFT, smaller boundary effects.

NOTE 8 ADDITIONAL STATEMENT ON DFT

Parseval Relation

$$\sum_{n=0}^{N-1} |x[n]|^2 = \frac{1}{N} \sum_{k=0}^{N-1} |X[k]|^2$$

$$= \frac{1}{N} \left(|X[0]|^2 + \left| X\left[\frac{N}{2}\right] \right|^2 + 2 \sum_{k=1}^{N/2-1} |X[k]|^2 \right)$$

Let $X[0] = \frac{1}{\sqrt{2}} X[0]$, $X[N/2] = \frac{1}{\sqrt{2}} X[N/2]$

$$\sum_{n=0}^{N-1} |x[n]|^2 = \frac{2}{N} \sum_{k=0}^{N/2} |X[k]|^2$$

New IDFT Equation

$$x[n] = \frac{1}{N} \left\{ \text{Re } X[0] + \text{Re } X[N/2](-1)^n + 2 \sum_{k=1}^{N/2-1} \text{Re } X[k] \cos(2\pi kn / N) - 2 \sum_{k=1}^{N/2-1} \text{Im } X[k] \sin(2\pi kn / N) \right\}$$

Let $X[0] = \frac{1}{\sqrt{2}} X[0]$, $X[N/2] = \frac{1}{\sqrt{2}} X[N/2]$

$$x[n] = \frac{2}{N} \sum_{k=0}^{N/2} \left\{ \text{Re } X[k] \cos(2\pi kn / N) - \text{Im } X[k] \sin(2\pi kn / N) \right\}$$

Convolution Equivalence of DFT

Let $h_k[n] = e^{j2\pi kn / N}$

$$X[k] = \sum_{i=0}^{N-1} x[i] h_k[0-i] = x[n] * h_k[n] |_{n=0}$$

Time Sampler of All Filters is 0.

Frequency Response

$$H_k[\omega] = \sum_{n=0}^{N-1} h_k[n] e^{-jn\omega} = \sum_{n=0}^{N-1} e^{-jn\omega} e^{j2\pi nk / N} = \frac{1 - e^{-jN\omega} e^{j2\pi k}}{1 - e^{-j\omega} e^{j2\pi k / N}}$$

Magnitude Response

$$|H_k[\omega]| = \frac{\sin(N\omega / 2 - \pi k)}{\sin(\omega / 2 - \pi k / N)}$$

Center Frequency $\omega_k = \frac{2\pi k}{N}$.

Frequency Leakage: when signal frequency ω is between ω_k and ω_{k+1} .

NOTE 9 FOURIER TRANSFORM PAIR

1. Frequency Response (FR)

- Delta Function

If $x[n] = \delta[n]$, then $X(\omega) = 1$.
 If $x[n] = \delta[n - m]$, then $X(\omega) = e^{-j\omega m}$.

- Square Function

Example 1:

If $x[n] = 1, n = 0, M-1$, then $X(\omega) = \frac{1 - e^{-j\omega M}}{1 - e^{-j\omega}}$ and $|X(\omega)| = \frac{\sin(\omega M / 2)}{\sin(\omega / 2)}$

Example 2:

If $x[n] = 1, |n| = 0, M$, then $X(\omega) = \frac{\sin(\omega(2M + 1) / 2)}{\sin(\omega / 2)}$.

If $y[n] = x[n - M]$, then $Y(\omega) = X(\omega) e^{-j\omega M}$
 If $y[n] = x[n] e^{jan}$, then $Y(\omega) = X(\omega - a)$

2. Discrete Fourier Transform (DFT)

- Delta Function

Time Region

If $x[n] = \delta[n], n=0, N-1$, then $X[k] = \text{DFT}(\delta[n]) = 1, k=0, N-1$.

If $x[n] = \delta[n - m], n=0, N-1$, then $X[k] = \text{DFT}(\delta[n - m]) = e^{-j2\pi km/N}, k=0, N-1$.

Magnitude $|X[k]| = 1$,

Phase $\text{Arg}(X[k]) = \arctan[\tan(-2\pi km/N)]$

Frequency Region

If $X[k] = \delta[k], k = 0, N-1$, then $x[n] = \text{IDFT}(\delta[k]) = \frac{1}{N}, n = 0, N-1$.

If $X[k] = \delta[k - M], k = 0, N-1$, then $x[n] = \text{IDFT}(\delta[k]) = \frac{1}{N} e^{j2\pi m n / N}, n = 0, N-1$.

- Square Function

Time Region:

Example 1: $x[n] = 1, n = 0, M-1$

$$X[k] = \sum_{n=0}^{M-1} e^{-j2\pi nk/N} = \frac{1 - e^{-j2\pi kM/N}}{1 - e^{-j2\pi k/N}} = e^{j\pi k(1-M)/N} \frac{\sin(\pi kM/N)}{\sin(\pi k/N)}$$

$$|X[k]| = \frac{\sin(\pi kM/N)}{\sin(\pi k/N)}$$

Example 2:

If $x[n] = 1, n = 0, M$ and $x[n] = 1, n = N - M, N - 1,$

$$\text{then } X[k] = \frac{\sin(\pi k(2M + 1) / N)}{\sin(\pi k / N)}$$

Frequency Region:

If $X[k] = 1,$ when $k = 0, M;$ and $X[k] = 1,$ when $k = N - M, N - 1,$

$$\text{then } x[n] = \frac{1}{N} \left(\sum_{k=0}^M e^{j2\pi kn / N} + \sum_{k=N-M}^{N-1} e^{2\pi kn / N} \right) = \frac{1}{N} \frac{\sin(\pi n(2M + 1) / N)}{\sin(\pi n / N)}$$

$$\text{DFT}(x[n - M]) = X[k] e^{-j2\pi kM / N}$$

$$\text{IDFT}(X[k - M]) = x[n] e^{j2\pi nM / N}$$

NOTE 10. FAST FOURIER TRANSFORM

FFT: Fast implementation of DFT

Signal Length $N = 2^L$

Let $x_1[r] = x[2r]$, $x_2[r] = x[2r + 1]$, $r = 0, N/2 - 1$

$$\begin{aligned} X[k] &= DFT(x[n]) \\ &= \sum_{r=0}^{N/2-1} x[2r]e^{-j2\pi(2r)k/N} + \sum_{r=0}^{N/2-1} x[2r+1]e^{-j2\pi(2r+1)k/N} \\ &= \sum_{r=0}^{N/2-1} x[2r]e^{-j2\pi rk/(N/2)} + e^{-j2\pi k/N} \sum_{r=0}^{N/2-1} x[2r+1]e^{-j2\pi rk/(N/2)} \\ &= X_1[k] + X_2[k]e^{-j2\pi k/N} \end{aligned}$$

($N/2$ dot FFT !!!)

1. For $k = 0, N/2 - 1$,

$$\boxed{X[k] = X_1[k] + X_2[k]e^{-j2\pi k/N}, \quad k = 0, N/2 - 1}$$

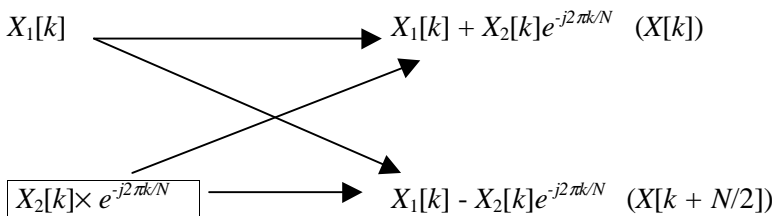
2. For $k = N/2, N - 1$,

Because

$$X_1[k + N/2] = X_1[k], \quad X_2[k + N/2] = X_2[k], \quad e^{-j2\pi(k + N/2)/N} = -e^{-j2\pi k/N}$$

$$\boxed{X[k + N/2] = X_1[k] - X_2[k]e^{-j2\pi k/N}, \quad k = 0, N/2 - 1}$$

Butterfly Algorithm



One Butterfly: generates 2 Dots of DFT

Each Layer: $N/2$ Butterflies

Each Butterfly: 1 multiply + 2 add

Layer Number: $L = \log_2 N$

Calculation Efficiency:

1. FFT Cost = $(N/2) \times L \times (1 \text{ Multiply} + 2 \text{ Add}) = \frac{N}{2} \log_2 N \text{ Multiply} + N \log_2 N \text{ Add}$

2. DFT Cost = $N^2 \text{ Multiply} + N(N - 1) \text{ Add}$

NOTE 11. FFT Application

Fast Convolution

For $x[n] * h[n]$, $x[n]$, $n = 0, M - 1$ and $h[n]$, $n = 0, L - 1$.

1. To Avoid Overlap, Zero-Extention

Choose $N = 2^J \geq (M + L - 1)$

$$x[n] = \begin{cases} x[n], & n = 0, M - 1 \\ 0, & n = M, N - 1 \end{cases}$$

$$h[n] = \begin{cases} h[n], & n = 0, L - 1 \\ 0, & n = L, N - 1 \end{cases}$$

2. Do FFT

$$X[k] = \text{FFT}(x[n]), H[k] = \text{FFT}(h[n]), k = 0, N - 1$$

3. Multiplication $Y[k] = X[k]H[k]$

$$4. \text{IFFT } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} Y[k] e^{j2\pi kn / N}$$

$$= \sum_{k=0}^{N-1} (\overline{Y[k] / N}) e^{-j2\pi kn / N}$$

$$y[n] = \overline{\text{FFT}(\overline{Y[k] / N})}$$

Calculation Efficiency Comparison

$$\text{Traditional Convolution } y[n] = \sum_{i=0, L-1} x[n-i]h[i], n = 0, L + M - 2.$$

Multiply: $(L + M - 1) \times L$

Add: $(L + M - 1) \times (L - 1)$

FFT Convolution

(1) $\text{FFT}(x[n]) + \text{FFT}(h[n]) + \text{FFT}(Y[k]/N)$

Multiply: $(3N / 2) \log_2 N$

Add: $3N \log_2 N$

(2) $(X[k]H[k]) + (Y[k] / N)$

Multiply: $2N$

Fast Correlation

$x[n], y[n], n = 0, M - 1$

$z[n] = x[n] * y[-n] = \sum_{i=0, M-1} x[i]y[i + n]$

Same Routine! (Zero-Extension + FFT)

$$\text{Just } Z[k] = X[k] \overline{Y[k]}$$

Calculation Efficiency

Traditional Correlation (Only Count Multiply!!)

$$\text{Cost} = M(2M - 1) \text{ Multiply}$$

FFT Correlation

$$\text{Cost} = (3N/2) \log_2 N + 2N \text{ Multiply}$$

Worst Case: Signal length of $x[n]$, $y[n]$

$$M = 2^L + 1$$

Then Extended Length: $N \geq 2M - 1 = 1 + 2^{L+1}$

$$\text{Thus, } N = 2^{L+2}$$

FFT Cost = $(6L + 20) 2^L$ Multiply,

while

Traditional Cost = $(1 + 2^L)(1 + 2^{L+1})$ Multiply

When $L \geq 5$, $M \geq 33$ dots, ($N \geq 128$)

FFT Method will be more Efficient than Traditional calculation.

NOTE 12. MULTIREOLUTION SPACES

Operator:

Down Sampling: If $y[n] = x[Mn]$, then $Y(\omega) = \frac{1}{M} \sum_{k=0}^{M-1} X\left(\frac{\omega - 2\pi k}{M}\right)$

Up Sampling: $y[l] = \begin{cases} x[n], & l = Mn \\ 0, & \text{others} \end{cases}$, then $Y(\omega) = X(M\omega)$

Scaling Function $\phi(x)$ is an Approximating Function .

If $\{\phi(x-n) \mid n \in Z\}$ is a Rieze basis of V_0 . Namely, exist unique sequence $\{C_0(n) \mid n \in Z\}$, for any function $f(x) \in V_0$, make $f(x) = \sum_n C_0[n]\phi(x-n)$.

Two-Scale Difference Equation $\phi(x/2) = 2 \sum_n h[n]\phi(x-n)$

Construct the Multiresolution Approximation

- (1) $V_m \subset V_{m-1}$
- (2) $f(x) \in V_m \Leftrightarrow f(2x) \in V_{m-1}$
- (3) $f(x) \in V_m \Rightarrow f(x-2^m n) \in V_m$
- (4) Exist two constants A and B, $0 < A \leq B$, that $A \|f\| \leq \sum_n |C_0[n]|^2 \leq B \|f\|$

Multi-Resolution Approximation (From Fine to Coarse)

For any $f(x) \in L^2(R)$,

$P_0 f(x) = \sum_n C_0[n]\phi(x-n)$, for V_0

$P_m f(x) = \sum_n C_m[n]\phi(2^{-m}x-n)$, for V_m

Ideal Low-Pass Function is a Scaling function

$\phi[x] = Sinc(\pi x)$

$\phi(x/2) = \sum_n Sinc\left(\frac{\pi n}{2}\right)\phi(x-n)$

$h[n] = \frac{1}{2} Sinc\left(\frac{\pi n}{2}\right)$

NOTE 13. WAVELET TRANSFORM

$$\begin{aligned}\phi_{m,n}(x) &= 2^{-m/2} \phi(2^{-m}x - n), & \psi_{m,n}(x) &= 2^{-m/2} \psi(2^{-m}x - n). \\ \phi(x/2) &= 2 \sum_n h[n] \phi(x - n), & \psi(x/2) &= 2 \sum_n g[n] \phi(x - n).\end{aligned}$$

$$\sum_n h[n] = 1, \quad \sum_n g[n] = 0$$

Scaling Transform

$$C_m[n] = \langle f(x), \phi_{m,n}(x) \rangle = \int_{-\infty}^{\infty} f(x) \phi_{m,n}(x) dx$$

Let $y = 2^{-j}x - k$

$$\begin{aligned}\phi_{m,n}(x) &= 2^{-m/2} \phi(2^{-m}x - n) \\ &= 2^{-m/2} \phi(y) = 2^{-m/2} \left\{ 2 \sum_k h[k] \phi(2y - k) \right\} \\ &= \sqrt{2} \sum_k h[k] \left\{ 2^{-(m-1)/2} \phi(2^{-(j-1)}x - 2n - k) \right\} \\ &= \sqrt{2} \sum_k h[k] \phi_{m-1, 2n+k}(x)\end{aligned}$$

$$\begin{aligned}C_m[n] &= \langle f(x), \phi_{m,n}(x) \rangle \\ &= \sqrt{2} \sum_k h[k] \langle f(x), \phi_{m-1, 2n+k}(x) \rangle \\ &= \sqrt{2} \sum_k h[k] C_{m-1}[2n+k]\end{aligned}$$

Wavelet Transform

$$D_m[n] = \langle f(x), \psi_{m,n}(x) \rangle = \int_{-\infty}^{\infty} f(x) \psi_{m,n}(x) dx$$

$$D_j[k] = \langle f, \psi_{j,k} \rangle$$

$$\begin{aligned}
\psi_{m,n}(x) &= 2^{-m/2} \psi(2^{-m}x - n) \\
&= 2^{-m/2} \psi(y) = 2^{-m/2} \left\{ 2 \sum_k g[k] \phi(2y - k) \right\} \\
&= \sqrt{2} \sum_k g[k] \left\{ 2^{-(m-1)/2} \phi(2^{-(j-1)}x - 2n - k) \right\} \\
&= \sqrt{2} \sum_k g[k] \phi_{m-1,2n+k}(x)
\end{aligned}$$

$$\begin{aligned}
D_m[n] &= \langle f(x), \psi_{m,n}(x) \rangle \\
&= \sqrt{2} \sum_k g[k] \langle f(x), \phi_{m-1,2n+k}(x) \rangle \\
&= \sqrt{2} \sum_k g[k] C_{m-1}[2n+k]
\end{aligned}$$

Properties of Orthonormal Bases

$$\begin{aligned}
\langle \phi(x), \phi(x-k) \rangle &= \delta[k] \\
\langle \phi(x), \psi(x-k) \rangle &= 0 \\
\langle \psi(x), \psi(x-k) \rangle &= \delta[k]
\end{aligned}$$

$$\int_{-\infty}^{\infty} \phi(x) dx = 1, \quad \int_{-\infty}^{\infty} \psi(x) dx = 0$$

If $f(x) \in V_0$,

$$f(x) = \sum_i C_0[i] \phi_{0,i}(x) = \sum_n C_1[n] \phi_{1,n}(x) + \sum_l D_1[l] \psi_{1,l}(x)$$

NOTE 14. DIGITAL IMPLEMENTATION

DISCRETE WAVELET DECOMPOSITION

$$\begin{aligned} C_m[n] &= \langle f(x), \phi_{m,n}(x) \rangle = \left\langle f(x), \sqrt{2} \sum_i h[i] \phi_{m-1,i+2n}(x) \right\rangle \\ &= \sqrt{2} \sum_i C_{m-1}[i] h[i-2n] \end{aligned}$$

$$\begin{aligned} D_m[n] &= \langle f(x), \psi_{m,n}(x) \rangle = \left\langle f(x), \sqrt{2} \sum_i g[i] \phi_{m-1,i+2n}(x) \right\rangle \\ &= \sqrt{2} \sum_i C_{m-1}[i] g[i-2n] \end{aligned}$$

WAVELET RECONSTRUCTION

$$\begin{aligned} V_m \oplus W_m &= V_{m-1} \\ P_m f &\Rightarrow V_m, Q_m f \Rightarrow W_m, P_m f + Q_m f = P_{m-1} f \end{aligned}$$

$$\begin{aligned} P_{m-1} f &= \sum_n C_{m-1}[n] \phi_{m-1,n}(x) \\ &= P_m f + Q_m f \\ &= \sum_i C_m[i] \phi_{m,i}(x) + \sum_l D_m[l] \psi_{m,l}(x) \end{aligned}$$

$$\begin{aligned} C_{m-1}[n] &= \left\langle \sum_i C_{m-1}[i] \phi_{m-1,i}(x), \phi_{m-1,n}(x) \right\rangle \\ &= \sum_i C_m[i] \langle \phi_{m,i}(x), \phi_{m-1,n}(x) \rangle + \sum_l D_m[l] \langle \psi_{m,l}(x), \phi_{m-1,n}(x) \rangle \\ &= \sum_i C_m[i] \left(\sqrt{2} \sum_k h[k] \langle \phi_{m-1,k+2i}(x), \phi_{m-1,n}(x) \rangle \right) + \sum_l D_m[l] \left(\sqrt{2} \sum_k g[k] \langle \psi_{m-1,k+2l}(x), \phi_{m-1,n}(x) \rangle \right) \\ &= \sqrt{2} \left(\sum_i C_m[i] h[n-2i] + \sum_l D_m[l] g[n-2l] \right) \end{aligned}$$

$$\text{Decomposition } C_m[n] = \sqrt{2} \sum_i C_{m-1}[i] h[i-2n], \quad D_m[n] = \sqrt{2} \sum_i C_{m-1}[i] g[i-2n].$$

$$\text{Reconstruction } C_{m-1}[n] = \sqrt{2} \left(\sum_i C_m[i] h[n-2i] + \sum_l D_m[l] g[n-2l] \right).$$

For Computer Implementation

$$\text{Decomposition } C_m[n] = \sum_i C_{m-1}[i]h[i-2n], \quad D_m[n] = \sum_i C_{m-1}[i]g[i-2n].$$

$$\text{Reconstruction } C_{m-1}[n] = 2 \times \left(\sum_i C_m[i]h[n-2i] + \sum_l D_m[l]g[n-2l] \right)$$

Perfect Reconstruction Condition

$$A(\omega) = H(\omega) \left[H^*(\omega)X(\omega) + H^*(\omega - \pi)X(\omega - \pi) \right]$$

$$B(\omega) = G(\omega) \left[G^*(\omega)X(\omega) + G^*(\omega - \pi)X(\omega - \pi) \right]$$

For Perfect Reconstruction:

$$X(\omega) = A(\omega) + B(\omega)$$

$$= X(\omega) \left[H(\omega)H^*(\omega) + G(\omega)G^*(\omega) \right] + X(\omega + \pi) \left[H(\omega)H^*(\omega - \pi) + G(\omega)G^*(\omega - \pi) \right]$$

$$\begin{aligned} |H(\omega)|^2 + |G(\omega)|^2 &= 1 \\ H(\omega)H^*(\omega - \pi) + G(\omega)G^*(\omega - \pi) &= 0 \end{aligned}$$

Conjugate Quadrature Filter (CQF)

Let

$$G(\omega) = H^*(\omega - \pi) \left[\pm e^{-j\omega(2M+1)} \right]$$

$$G(\omega - \pi) = -H^*(\omega) \left[\pm e^{j\omega(2M+1)} \right]$$

Then $H(\omega)H^*(\omega - \pi) + G(\omega)G^*(\omega - \pi) = 0$

$$\begin{aligned} |H(\omega)|^2 + |H(\omega - \pi)|^2 &= 1 \\ |G(\omega)|^2 + |G(\omega - \pi)|^2 &= 1 \end{aligned}$$

CQF Example (Let $M = 0$)

$$G(\omega) = H^*(\omega - \pi)e^{-j\omega}, \quad g[k] = (-1)^{1-k} h[1-k]$$

$$G(\omega) = -H^*(\omega - \pi)e^{-j\omega}, \quad g[k] = (-1)^k h[1-k]$$

Operator: Down Sampling

$$y[n] = x[Mn]$$

$$Y(\omega) = \frac{1}{M} \sum_{k=0}^{M-1} X\left(\frac{\omega - 2\pi k}{M}\right)$$

Proof:

$$Y(\omega) = \frac{1}{M} \sum_{k=0}^{M-1} \sum_{l=0}^{N-1} x[l] e^{-j(\omega - 2\pi k)l/M} = \frac{1}{M} \sum_{l=0}^{N-1} x[l] e^{-j\omega l/M} \sum_{k=0}^{M-1} e^{j2\pi k l/M}$$

$$\text{Only when } l = Mn, \quad \sum_{k=0}^{M-1} e^{j2\pi k l/M} = M$$

$$\text{else } \sum_{k=0}^{M-1} e^{j2\pi k l/M} = 0 \quad (\text{think Why ??})$$

$$\text{Thus } Y(\omega) = \sum_{n=0}^{N/M-1} x[Mn] e^{j\omega n}$$

$$y[n] = x[Mn]$$

Operator: Up Sampling

$$y[l] = \begin{cases} x[n], & l = Mn \\ 0, & \text{others} \end{cases}$$

$$Y(\omega) = x(M\omega)$$

Proof:

$$Y(\omega) = \sum_l y[l] e^{-j\omega l} = \sum_l x[n] e^{-j\omega Mn} = X(M\omega)$$

LAST REVIEW NOTE

1. Linear System

Finite vs. Infinite Duration Signals

Right-sided, Left-sided, and Two-sided Signals

The terms apply only to infinite duration signals.

Causal and Anti-Causal Signals

Zero phase, Linear phase and Nonlinear phase signals

Time Delay.

Linear System:

(1) Homogeneity.

(2) Additivity.

(3) Commutative.

Shift (Time) Invariance System.

Energy and Stability.

2. Convolution

Delta Function $\delta[n]$.

Standard Function $u[n]$.

$$\delta[n] = u[n] - u[n-1]$$

$$u[n] = \sum_{k=0}^{\infty} \delta(n-k)$$

Impulse response $h[n]$.

The signal that exits a system when a Delta Function (unit impulse) is the input.

$$h[n] = S(\delta[n])$$

Convolution $y[n] = h[n] * x[n]$

$$y[i] = \sum_{j=-\infty}^{\infty} h[j]x[i-j]$$

Properties of Delta function: $\delta[n]$ is identity for convolution.

$$\delta[n] * x[n] = x[n]$$

$$x[n] * k\delta[n] = kx[n]$$

$$x[n] * \delta[n+s] = x[n+s]$$

3. Fourier Representation

Fourier Response

$$X(\omega) = \sum_{n=-\infty}^{+\infty} x(n)e^{-j\omega n}$$

$$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\omega)e^{jn\omega} d\omega$$

$$X(\omega) = X(\omega + 2\pi)$$

Discrete Fourier Transform (DFT)

$$x[n+N] = x[n]$$

$$X[k] = \sum_{n=0}^{N-1} x[n]e^{-j2\pi kn/N}$$

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k]e^{j2\pi kn/N}$$

$$X[k+N] = X[k]$$

Frequency Response of Sequence $h[n]$

$$H(\omega) = \sum_{n=-\infty}^{+\infty} h(n)e^{-j\omega n}$$

$$H(\omega) = \frac{Y(\omega)}{X(\omega)}$$

$$|H(\omega)| = \sqrt{\text{Im} H(\omega)^2 + \text{Re} H(\omega)^2} \quad \text{Magnitude of Transfer Function}$$

$$\text{Arg}(H(\omega)) = \arctan\left(\frac{\text{Im}H(\omega)}{\text{Re}H(\omega)}\right) \quad \text{Phase of Transfer Function}$$

Ideal Low-pass Filter

$$H(\omega) = \begin{cases} 1, & |\omega| \leq \frac{\pi}{2} \\ 0, & \frac{\pi}{2} < |\omega| \leq \pi \end{cases}$$

$$h[n] = \frac{\sin\left(\frac{k\pi}{2}\right)}{k\pi}, \quad h[2k] = 0.$$

Frequency Transform of Convolution

$$y[n] = h[n] * x[n], \quad \text{then } Y(\omega) = X(\omega)H(\omega)$$

$$X(\omega) = \sum_{n=-\infty}^{+\infty} x(n)e^{-j\omega n}$$

$$y[n] = x[-n], \quad Y(\omega) = X^*(\omega) \text{ or } X(-\omega)$$

4. Fourier Pairs

Frequency Response

Delta Function

$$x[n] = \delta[n], \quad X(\omega) = 1$$

$$x[n] = \delta[n - m], \quad X(\omega) = e^{-jm\omega}$$

Square Function

Example 1:

$$x[n] = 1, \quad n = 0, M-1$$

$$X(\omega) = \frac{1 - e^{-jM\omega}}{1 - e^{-j\omega}}$$

Example 2:

$$x[n] = 1, |n| = 0, M$$

$$X(\omega) = \frac{\sin\left(\frac{\omega(2M+1)}{2}\right)}{\sin\left(\frac{\omega}{2}\right)}$$

$$y[n] = x[n - M], Y(\omega) = X(\omega)e^{-j\omega M}$$

$$y[n] = x[n]e^{jan}, Y(\omega) = X(\omega - a)$$

DFT

Delta Function

$$X[k] = \text{DFT}(\delta[n]) = 1$$

$$X[k] = \text{DFT}(\delta[n - m]) = e^{-j2\pi km/N}$$

$$X[k] = \delta[k], x[n] = \frac{1}{N}$$

$$X[k] = \delta[k - M], x[n] = \frac{e^{j2\pi nM/N}}{N}$$

Square Function

$$x[n] = 1, n = 0, M - 1$$

$$X[k] = \frac{1 - e^{-j2\pi kM/N}}{1 - e^{-j2\pi k/N}} = e^{j\pi k(1-M)/N} \frac{\sin(\pi kM/N)}{\sin(\pi k/N)}$$

$$x[n] = 1, n = 0, M; \text{ and } x[n] = 1, n = N - M, N - 1.$$

$$X[k] = \frac{\sin(\pi k(2M+1)/N)}{\sin(\pi k/N)}$$

Frequency Region:

$$X[k] = 1, \text{ when } k = 0, M;$$

$$X[k] = 1, \text{ when } k = N - M, N - 1.$$

$$\text{Then } x[n] = \frac{1}{N} \frac{\sin(\pi n(2M+1)/N)}{\sin(\pi n/N)}$$

$$\text{DFT}(x[n - M]) = X[k]e^{-j2\pi kM/N}$$

$$\text{IDFT}(X[k - M]) = x[n]e^{j2\pi nM/N}$$

5. FAST FOURIER TRANSFORM

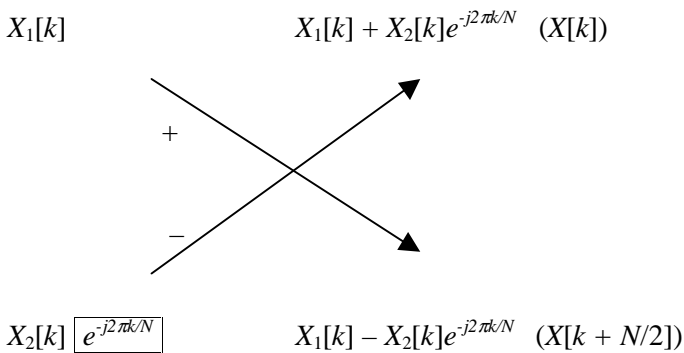
Signal Length $N = 2^L$

Let $x_1[r] = x[2r]$, $x_2[r] = x[2r + 1]$, $r = 0, N/2 - 1$.

$$X[k] = X_1[k] + X_2[k]e^{-j2\pi k/N}, \quad k = 0, N/2 - 1.$$

$$X[k + N/2] = X_1[k] - X_2[k]e^{-j2\pi k/N}, \quad k = 0, N/2 - 1.$$

Butterfly Algorithm



One Butterfly: generates 2 Dots of DFT

Each Layer: $N/2$ Butterflies

Each Butterfly: 1 multiply + 2 add

Layer Number: $L = \log_2 N$

Calculation Efficiency:

$$\text{FFT Cost} = (N/2) \times L \times (1 \text{ Multiply} + 2 \text{ Add})$$

$$= \frac{N}{2} \log_2 N \text{ Multiply} + N \log_2 N \text{ Add}$$

$$\text{DFT Cost} = N^2 \text{ Multiply} + N(N - 1) \text{ Add}$$

Filter

Finite Impulse Response (FIR) filter – Finite Convolution

Infinite Impulse Response (IIR) filter – Recursion

Low-pass, High-pass, Band-pass, and Band-reject filters

6. Wavelet

Operator: Down Sampling

$$y[n] = x[Mn]$$

$$Y(\omega) = \frac{1}{M} \sum_{k=0}^{M-1} X\left(\frac{\omega - 2\pi k}{M}\right)$$

Operator: Up Sampling

$$y[l] = \begin{cases} x[n], & l = Mn \\ 0, & \text{others} \end{cases}$$

$$Y(\omega) = X(M\omega)$$

$$\phi_{m,n}(x) = 2^{-m/2} \phi(2^{-m}x - n), \quad \psi_{m,n}(x) = 2^{-m/2} \psi(2^{-m}x - n).$$

$$\phi(x/2) = 2 \sum_n h[n] \phi(x - n), \quad \psi(x/2) = 2 \sum_n g[n] \phi(x - n).$$

$$\sum_n h[n] = 1, \quad \sum_n g[n] = 0$$

$$\text{Decomposition } C_m[n] = \sqrt{2} \sum_i C_{m-1}[i] h[i - 2n], \quad D_m[n] = \sqrt{2} \sum_i C_{m-1}[i] g[i - 2n].$$

$$\text{Reconstruction } C_{m-1}[n] = \sqrt{2} \left(\sum_i C_m[i] h[n - 2i] + \sum_l D_m[l] g[n - 2l] \right).$$

For Computer Implementation

$$\text{Decomposition } C_m[n] = \sum_i C_{m-1}[i] h[i - 2n], \quad D_m[n] = \sum_i C_{m-1}[i] g[i - 2n].$$

$$\text{Reconstruction } C_{m-1}[n] = 2 \times \left(\sum_i C_m[i] h[n - 2i] + \sum_l D_m[l] g[n - 2l] \right)$$

Perfect Reconstruction Condition

$$\begin{aligned} |H(\omega)|^2 + |G(\omega)|^2 &= 1 \\ H(\omega)H^*(\omega - \pi) + G(\omega)G^*(\omega - \pi) &= 0 \end{aligned}$$

Conjugate Quadrature Filter (CQF)

$$G(\omega) = H^*(\omega - \pi) \left[\pm e^{-j\omega(2M+1)} \right]$$

$$\text{Then } H(\omega)H^*(\omega - \pi) + G(\omega)G^*(\omega - \pi) = 0$$

$$\begin{aligned} |H(\omega)|^2 + |H(\omega - \pi)|^2 &= 1 \\ |G(\omega)|^2 + |G(\omega - \pi)|^2 &= 1 \end{aligned}$$

CQF Example (Let $M = 0$)

$$G(\omega) = H^*(\omega - \pi)e^{-j\omega}, \quad g[k] = (-1)^{1-k} h[1-k].$$

$$G(\omega) = -H^*(\omega - \pi)e^{-j\omega}, \quad g[k] = (-1)^k h[1-k].$$